Leandro G. Barajas, Ph.D., PMP

L.G.Barajas@ieee.org - www.LeandroBarajas.com

QUALIFICATIONS SUMMARY

Creative, effective, and accomplished manager and expert in robotics and automation with multidisciplinary experience in R&D, systems integration and technology management at a global scale for product, service, and manufacturing applications. Broad applied expertise in project management, global collaboration, external funding & leveraging, intellectual property management, technology & strategy planning, innovation forecasting & road mapping as well as technology transfer. Distinguished with **over 60 corporate, academic, and professional awards**. Authored over **60 technical publications, 40 patents & patent applications**, 7 Defensive Publications, and 9 Trade Secrets. Elected IEEE Senior member and AIAA Associate Fellow.

EDUCATION

2000- 2003	GEORGIA INSTITUTE OF TECHNOLOGY, Atlanta, GA, USA
	Doctor of Philosophy (Ph.D.) in Electrical & Computer Engineering.
1999-2000	GEORGIA INSTITUTE OF TECHNOLOGY, Atlanta, GA, USA
	Master of Science (M.S.) in Electrical & Computer Engineering
	 Major in Control Systems & DSP; Minor in Mathematics
1991-1996	Universidad Distrital Francisco José de Caldas, Bogotá, Colombia
	Bachelor of Science (B.S.) in Electrical Engineering, Class Valedictorian
	- Major in Telecommunications & Control Systems ; Minor in Medical Electronics

INDUSTRY EXPERIENCE

	INDUSTRY EXPERIENCE		
DYNETICS, INC., MISSILE AND AVIATION SYSTEMS DIVISION, HUNTSVILLE, AL			
2012-Present Principal Eng. & Section Manager. Unmanned Systems and Aerodynamics Department			
GENERAL MOTORS, GM R&D, MANUFACTURING SYSTEMS RESEARCH LABORATORY			
2008-2012	Staff Researcher. Advanced Robotics Group		
2007-2008	Senior Plant Engineer. Orion (MI) General Assembly Plant		
2006-2007	Senior Manufacturing Engineer. ME, Controls, Conveyors, Robotics & Welding Division		
2003-2006	Senior Research Engineer. Plant Floor Systems & Controls Group		
GEORGIA INSTITUTE OF TECHNOLOGY, MANUFACTURING RESEARCH CENTER (MARC), ATLANTA, GA.			
1999-2003	Graduate Research Assistant. Center for Board Assembly Research		

TECHNICAL SKILLS Engineering: Matlab/Simulink, Minitab, MathCAD, Mathematica, Maple, QFD Capture, DExpert,

5	
	LabVIEW, NI-DAQ, Excel Programming, R, WEKA, Wireshark, PuTTY
Robotics:	Robot Operating System (ROS), Microsoft Robotics Developer Studio, Industrial Robotics,
	Humanoid Robotics, Obstacle Avoidance, Simultaneous Localization and Mapping
	(SLAM), Kalman Filtering, Particle Filters, Sensor Fusion, PID Control, Adaptive Control
	Robot Vision, Motion Planning, Object Grasping and Manipulation, Imitation Learning,
	Machine Learning, Diagnostics, Prognostics and Health Management
Techniques:	Data Mining, Big Data Analytics, Statistical Analysis, Clustering, Classification, Predictive
	Analytics, Anomaly Detection, Genetic Algorithms, Neural Networks, Data Reduction,
	Regression, Sequence Mining, System Identification, Support Vector Machines, Model
	Checking, Data Visualization

Comp. Vision: OpenCV, Matlab IP/IA, MVTech Halcon, Cognex Vision	ionPro, Labview NI Vision/IMAQ, ORB,
SIFT, SURF, Keypoint Detectors and Descriptors,	Object Classification and Clustering,
Visual Servoing, Image Segmentation, Semantic Lab	peling

Programming: Microsoft Visual Studio .NET (C#, VB, C++), VBA, Java, JavaScript, Python, PHP, C++, C,
Dynamic C, SQL, XML, HTML, UML, Fortran, Perl, Delphi, Pascal, Arduino, Processing,
AutoHotkey and assembler for TMS320Cxx. x86, Z80, 68xxx, PIC and 8051/52

CAD/CAE: Solidworks, Polyworks, Meshlab, Blender, AT-3D, Open CASCADE, AutoCAD, Makerbot Desktop, PSpice, Multisim (Electronics Workbench), Electra E7 for Visio, OrCAD and Eagle DSS/CCR, XML, TCP/IP, UDP, SOAP, Modbus; IEEE 802.x: WiFi, Bluetooth, Zigbee, WiMax,

Telecomms: DSS/CCR, XML, TCP/IP, UDP, SOAP, Modbus; IEEE 802.x: WiFi, Bluetooth, Zigbee, WiMax, Ethernet; Serial Communications: RS-232, RS-422, RS-485, LVDS, SPI, I2C, OneWire, USB, Fiber Charged, AM, STD 15534 (B.

Fiber Channel, MIL-STD-1553A/B